# Motion in Two-Dimensions Source and Sink(12) 

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October 16, 2020

## 1 Stream function or current function

Let $u$ and $v$ be the components of velocity in two-dimensional motion. The the differential equation of streamline flow, is given by

$$
\begin{equation*}
\frac{d x}{u}=\frac{d y}{v} \quad \text { or } \quad v d x-u d y=0 \tag{1}
\end{equation*}
$$

and the equation of continuity of fluid flow is

$$
\begin{equation*}
\frac{\partial u}{\partial x}+\frac{\partial v}{\partial y}=0 \quad \text { or } \quad \frac{\partial v}{\partial y}=\frac{\partial(-u)}{\partial x} \tag{2}
\end{equation*}
$$

Equation (2) be exact condition for the differential equation (1). so solution of equation must be in the form $d \psi=0$ such that

$$
\begin{equation*}
d \psi=\frac{\partial \psi}{\partial x} d x+\frac{\partial \psi}{\partial y}=v d x-u d y=0 \tag{3}
\end{equation*}
$$

so that

$$
u=-\frac{\partial \psi}{\partial y} \quad v=\frac{\partial \psi}{\partial x}
$$

and

$$
d \psi=0 \quad \Longrightarrow \psi=C \quad(\text { Constant })
$$

This function $\psi$ is known as stream function. Thus the stream function is constant along a streamline motion. Clearly current function is exist by virtue of the equation of continuity and incompressibile=ity of the fluid. Hence current function exists in all type of two-dimensional motion wheather rotational or irrotational.

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### 1.1 Physical Significance of stream function

Let $L M$ be any curve in the $x-y$ plane and $\psi_{1}$ and $\psi_{2}$ be stream function at $L$ and $M$ respectively. Let $P$ be an arbitrary point on $L M$ such that $\operatorname{arc} L P=s$ and $Q$ be a neighbouring point on $L M$ such that $\operatorname{arc} L Q=s+\delta s$. Let $\theta$ be the angle between tangent at $P$ and $x$-axis. If $u$ and $v$ be the velocity components at point $P$, then


$$
\begin{equation*}
\text { velocity at } \mathrm{P} \text { along inward drawn normal } \mathrm{PN}=v \cos \theta-u \sin \theta \tag{4}
\end{equation*}
$$

when $\psi$ is the stream function, then we have

$$
\begin{equation*}
u=-\frac{\partial \psi}{\partial y} \quad \text { and } \quad v=\frac{\partial \psi}{\partial x} \tag{5}
\end{equation*}
$$

Also from calculus

$$
\begin{equation*}
\cos \theta=\frac{d x}{d s} \quad \text { and } \quad \sin \theta=\frac{d y}{d s} \tag{6}
\end{equation*}
$$

Using equation (4), we get

$$
\begin{equation*}
\text { flux across PQ from right to left }=(v \cos \theta-u \sin \theta) \delta s \tag{7}
\end{equation*}
$$

$\therefore$ Total flux for curve $L M$ from right to left

$$
=\int_{L M}(v \cos \theta-u \sin \theta) d s=\int_{L M}\left(\frac{\partial \psi}{\partial x} \frac{d x}{d s}+\frac{\partial \psi}{\partial y} \frac{d y}{d s}\right) d s
$$

$$
\int_{L M}\left(\frac{\partial \psi}{\partial x} d x+\frac{\partial \psi}{\partial y} d s=\int_{\psi_{1}}^{\psi_{2}}\left(\frac{\partial \psi}{\partial x} d x+\frac{\partial \psi}{\partial y} d s\right)=\int_{\psi_{1}}^{\psi_{2}} d \psi=\psi_{1}-\psi_{2}\right.
$$

Thus a property of the current function is that the difference of its values at two points respond the flow across any line joining the points.

Remark 1. Since the velocity normal to $\delta s$ will contribute to the flux across $\delta s$ where as the velocity along tangent to $\delta s$ will not contribute towards flux across $\delta s$, we have

$$
\begin{array}{r}
\text { flux across } \delta s=\delta s \times \text { normal velocity } \\
(\psi+\delta \psi)-\psi=\delta s \times \text { velocity from right to left across } \\
\text { velocity from right to left across } \delta s=\frac{\partial \psi}{\partial s} \tag{8}
\end{array}
$$

Remark 2. Velocity components in terms of $\psi$ in plane-polar coordinate $(r, \theta)$ can be obtained by using the method in remarks (1). Let $q_{r}$ and $q_{\theta}$ be velocity components in the direction $r$ and $\theta$ increasing respectively. Then

$$
\begin{array}{r}
q_{r}=\text { velocity from right to left across } r \delta \theta \\
=\lim _{\delta \theta \rightarrow 0} \frac{\delta \psi}{r \delta \theta}=\frac{1}{r} \frac{\partial \psi}{\partial \theta} \\
\text { and } \quad \begin{array}{r}
q_{\theta}
\end{array} \\
=\text { velocity from right to left across } \delta r \\
=\lim _{\delta r \rightarrow 0} \frac{\delta \psi}{\delta r}=\frac{\partial \psi}{\partial r}  \tag{9}\\
\text { Thus } \quad q_{r}=\frac{1}{r} \frac{\partial \psi}{\partial \theta} \quad \text { and } \quad q_{\theta}=\frac{\partial \psi}{\partial r}
\end{array}
$$

### 1.2 Basic concept of complex valued function of complex variable

Suppose $z=x+\iota y$ and that $w=f(z)=\phi(x, y)+\iota \psi(x, y)$, where $x, y, \phi, \psi \in \mathbb{R}$. Also suppose that $\phi$ and $\psi$ and their derivatives are everywhere continuous within a domain. If at any point $Z$ of its domain the derivatives $d w / d z=f^{\prime}(z)$ is unique, then $w$ is is said to be analytic at that point. If $w$ is analytic throughout the domain is said analytic or regular throughout the domain. If this is analytic throughout the domain then must satisfied the necessary and sufficient condition for $w$

$$
\begin{equation*}
\frac{\partial \phi}{\partial x}=\frac{\partial \psi}{\partial y} \text { and } \frac{\partial \phi}{\partial y}=-\frac{\partial \psi}{\partial x} \tag{10}
\end{equation*}
$$

which are known Cuchy-Riemann (C-R) equations. The function $\phi$ and $\psi$ are known as conjugate functions.

## Remark 3.

$$
f_{x}(z)=\frac{\partial \phi}{\partial x}+\iota \frac{\partial \psi}{\partial x}
$$

and

$$
\begin{gathered}
f_{y}(z)=\frac{\partial \phi}{\partial y}+\iota \frac{\partial \psi}{\partial y} \\
\Longrightarrow \quad \frac{\partial \phi}{\partial y}+\iota \frac{\partial \psi}{\partial y}=\iota\left(\frac{\partial \phi}{\partial x}+\iota \frac{\partial \psi}{\partial x}\right)
\end{gathered}
$$

We get another form of $C$ - $R$ equation

$$
\iota f_{x}(z)=f_{y}(z)
$$

Remark 4. Since $z=x+\iota y$ that implies $\bar{z}=x-\iota y$, then $x=\frac{z+\bar{z}}{2}$ and $y=\frac{z-\bar{z}}{2 \iota}$ We get We get another form of $C$ - $R$ equation

$$
\frac{\partial^{2} f}{\partial z \partial \bar{z}}=0
$$

All the best...
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