## Motion in Two-Dimensions Source and Sink(12)

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## **1** Stream function or current function

Let u and v be the components of velocity in two-dimensional motion. The the differential equation of streamline flow, is given by

$$\frac{dx}{u} = \frac{dy}{v} \quad \text{or} \quad vdx - udy = 0 \tag{1}$$

and the equation of continuity of fluid flow is

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \quad \text{or} \quad \frac{\partial v}{\partial y} = \frac{\partial (-u)}{\partial x}$$
 (2)

Equation (2) be exact condition for the differential equation (1). so solution of equation must be in the form  $d\psi = 0$  such that

$$d\psi = \frac{\partial\psi}{\partial x}dx + \frac{\partial\psi}{\partial y} = vdx - udy = 0$$
(3)

so that

$$u = -\frac{\partial \psi}{\partial y}$$
  $v = \frac{\partial \psi}{\partial x}$ 

and

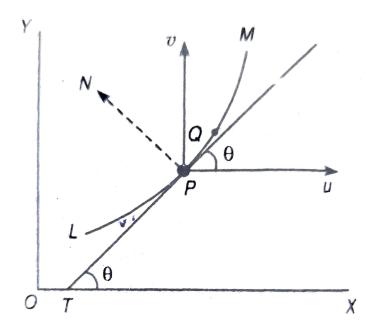
$$d\psi = 0 \implies \psi = C$$
 (Constant)

This function  $\psi$  is known as stream function. Thus the stream function is constant along a streamline motion. Clearly current function is exist by virtue of the equation of continuity and incompressibile=ity of the fluid. Hence current function exists in all type of two-dimensional motion wheather rotational or irrotational.

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## 1.1 Physical Significance of stream function

Let LM be any curve in the x - y plane and  $\psi_1$  and  $\psi_2$  be stream function at L and M respectively. Let P be an arbitrary point on LM such that  $\operatorname{arc} LP = s$  and Q be a neighbouring point on LM such that  $\operatorname{arc} LQ = s + \delta s$ . Let  $\theta$  be the angle between tangent at P and x- axis. If u and v be the velocity components at point P, then



velocity at P along inward drawn normal  $PN = v \cos \theta - u \sin \theta$  (4) when  $\psi$  is the stream function, then we have

$$u = -\frac{\partial \psi}{\partial y}$$
 and  $v = \frac{\partial \psi}{\partial x}$  (5)

Also from calculus

$$\cos \theta = \frac{dx}{ds}$$
 and  $\sin \theta = \frac{dy}{ds}$  (6)

Using equation (4), we get

flux across PQ from right to left = 
$$(v\cos\theta - u\sin\theta)\delta s$$
 (7)

 $\therefore$  Total flux for curve LM from right to left

$$= \int_{LM} (v\cos\theta - u\sin\theta) ds = \int_{LM} \left(\frac{\partial\psi}{\partial x}\frac{dx}{ds} + \frac{\partial\psi}{\partial y}\frac{dy}{ds}\right) ds$$

$$\int_{LM} \left( \frac{\partial \psi}{\partial x} dx + \frac{\partial \psi}{\partial y} ds = \int_{\psi_1}^{\psi_2} \left( \frac{\partial \psi}{\partial x} dx + \frac{\partial \psi}{\partial y} ds \right) = \int_{\psi_1}^{\psi_2} d\psi = \psi_1 - \psi_2$$

Thus a property of the current function is that the difference of its values at two points respond the flow across any line joining the points.

**Remark 1.** Since the velocity normal to  $\delta s$  will contribute to the flux across  $\delta s$  where as the velocity along tangent to  $\delta s$  will not contribute towards flux across  $\delta s$ , we have

flux across 
$$\delta s = \delta s \times normal velocity$$
  
 $(\psi + \delta \psi) - \psi = \delta s \times velocity from right to left across$   
 $velocity from right to left across$   $\delta s = \frac{\partial \psi}{\partial s}$ 
(8)

**Remark 2.** Velocity components in terms of  $\psi$  in plane-polar coordinate  $(r, \theta)$  can be obtained by using the method in remarks (1). Let  $q_r$  and  $q_{\theta}$  be velocity components in the direction r and  $\theta$  increasing respectively. Then

$$q_{r} = \text{ velocity from right to left across } r\delta\theta$$

$$= \lim_{\delta\theta \to 0} \frac{\delta\psi}{r\delta\theta} = \frac{1}{r} \frac{\partial\psi}{\partial\theta}$$
and  $q_{\theta} = \text{ velocity from right to left across } \delta r$ 

$$= \lim_{\delta r \to 0} \frac{\delta\psi}{\delta r} = \frac{\partial\psi}{\partial r}$$
Thus  $q_{r} = \frac{1}{r} \frac{\partial\psi}{\partial\theta}$  and  $q_{\theta} = \frac{\partial\psi}{\partial r}$ 
(9)

## 1.2 Basic concept of complex valued function of complex variable

Suppose  $z = x + \iota y$  and that  $w = f(z) = \phi(x, y) + \iota \psi(x, y)$ , where  $x, y, \phi, \psi \in \mathbb{R}$ . Also suppose that  $\phi$  and  $\psi$  and their derivatives are everywhere continuous within a domain. If at any point Z of its domain the derivatives dw/dz = f'(z) is unique, then w is is said to be analytic at that point. If w is analytic throughout the domain is said analytic or regular throughout the domain. If this is analytic throughout the domain then must satisfied the necessary and sufficient condition for w

$$\frac{\partial \phi}{\partial x} = \frac{\partial \psi}{\partial y}$$
 and  $\frac{\partial \phi}{\partial y} = -\frac{\partial \psi}{\partial x}$  (10)

which are known Cuchy-Riemann (C-R) equations. The function  $\phi$  and  $\psi$  are known as conjugate functions.

Remark 3.

$$f_x(z) = \frac{\partial \phi}{\partial x} + \iota \frac{\partial \psi}{\partial x}$$

and

$$f_y(z) = \frac{\partial \phi}{\partial y} + \iota \frac{\partial \psi}{\partial y}$$
$$\implies \quad \frac{\partial \phi}{\partial y} + \iota \frac{\partial \psi}{\partial y} = \iota (\frac{\partial \phi}{\partial x} + \iota \frac{\partial \psi}{\partial x})$$

We get another form of C-R equation

$$\iota f_x(z) = f_y(z)$$

**Remark 4.** Since  $z = x + \iota y$  that implies  $\overline{z} = x - \iota y$ , then  $x = \frac{z + \overline{z}}{2}$  and  $y = \frac{z - \overline{z}}{2\iota}$  We get we get another form of C-R equation

$$\frac{\partial^2 f}{\partial z \partial \bar{z}} = 0$$

All the best... Next in 13th Econtent