## M.S c Mathematics –SEM 3 Rigid Dynamics

CC-13 Unit 1

## E-content – Pro(Dr)L N RAI

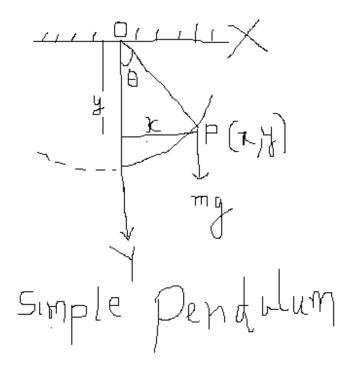
## HOD, PG Department of Mathematics, Patna University, Patna.

## **Topic- Equation of motion for a simple pendulum**

Equation of motion for a simple pendulum of length I and mass of the bob 'm' by using Lagrange's equation

Solution:

Let  $oldsymbol{ heta}$  be the angular displacement from the vertical OY at any time t. This is shown below



The dynamical system consists of a single particle of mass m and generalised co-ordinate

We have Lagrange's equation of motion

$$\frac{d}{dt}\left(\frac{\partial L}{\partial \theta}\right) - \frac{\partial L}{\partial \theta} = 0^{\dots(1)}$$

Here

$$T = \frac{1}{2}ml^{2}\dot{\theta}^{2} \text{ and } V = -mgLcos\theta$$
$$L = T - V$$
$$= \frac{1}{2}ml^{2}\dot{\theta}^{2} + mgLcos\theta$$

Substituting the value of L in equation (1), we obtain

$$\frac{d}{dt}(ml^{2}\dot{\theta}^{2}) + mgLcos\theta = 0$$
$$ml^{2}\dot{\theta}^{2} + mgLcos\theta = 0$$
$$\ddot{\theta} + \frac{g}{l}sin\theta = 0.....(ii)$$

This is the required equation of motion.