

# LPP (Simplex Method)

## (M.Sc. Sem-III)

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**Definition (Basic Solution) :** Given a system of  $m$  simultaneous linear equations in  $n$  unknowns ( $m < n$ )

$$Ax = b, x^T \in R^n,$$

Where  $A$  is an  $m \times n$  matrix of rank  $m$ . Let  $B$  be any  $m \times m$  submatrix, formed by  $m$  linearly independent columns of  $A$ . Then, a solution obtained by setting  $n - m$  variables not associated with the columns of  $B$ , equal to zero, and solving the resulting system, is called a **basic solution** to the given system of equations.

The  $m$  variables, which may be all different from zero, are called **basic variables**. The  $m \times m$  non-singular sub-matrix  $B$  is called a **basic matrix** with the columns of  $B$  as **basic vectors**.

**Remarks :** The name basic solution, as used above, merits a word of caution. If  $B$  is the basis sub-matrix chosen, then the basic solution to the system is

$$x_B = B^{-1}b.$$

But  $x_B^T \in R^m$ , and as such cannot be called a solution of the given system. Truly speaking, if  $x_B$  is a basic solution, then a solution to the given system is  $\begin{bmatrix} x_B^T, 0 \end{bmatrix}$  where  $x_B^T \in R^m$ , and  $0 \in R^{n-m}$ . However, we shall follow the current usage and call  $x_B$  a basic solution of the given system, remembering all the time that the actual solution is  $\begin{bmatrix} x_B^T, 0 \end{bmatrix}$ .

**Definition (Degenerate solution).** A basic solution to the system is called **degenerate** if one or more of the basic variables vanish.

### SAMPLE PROBLEMS

1. Obtain all the basic solutions to the following system of linear equation :

$$x_1 + 2x_2 + x_3 = 4$$

$$2x_1 + x_2 + 5x_3 = 5.$$

Sol. The given system of equations can be written in the matrix form as  $Ax = b$ , where

$$A = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 1 & 5 \end{pmatrix}, x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \text{ and } b = \begin{bmatrix} 4 \\ 5 \end{bmatrix}.$$

Since, rank of  $A$  is 2, the maximum number of linearly independent columns of  $A$  is 2. Thus, we can take any of the following,  $2 \times 2$  sub-matrices as basic matrix  $B$  :

$$\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 2 & 5 \end{pmatrix} \text{ and } \begin{pmatrix} 2 & 1 \\ 1 & 5 \end{pmatrix}$$

The variables not associated with the columns of  $B$  are  $x_3$ ,  $x_2$  and  $x_1$  respectively, in the three different cases.

Let us first take  $B = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$ . A basic solution to the given system is now obtained by setting  $x_3 = 0$ , and solving the system.

$$\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 4 \\ 5 \end{bmatrix}$$

Thus, a basic (non-basic) solution to the given system is :

$$\text{(Basic)} x_1 = 2, x_2 = 1; \quad \text{(Non-basic)} x_3 = 0$$

Similarly, the other two basic and non-basic solutions are :

$$\text{(Basic)} x_1 = 5, x_2 = -1; \quad \text{(Non-basic)} x_3 = 0$$

$$\text{and} \quad \text{(Basic)} x_2 = 5/3, x_3 = 2/3; \quad \text{(Non-basic)} x_1 = 0$$

We observe that all the above three basic solutions are non-degenerate.

2. Show that the following system of linear equations has a degenerate solution :

$$2x_1 + x_2 - x_3 = 2$$

$$3x_1 + 2x_2 + x_3 = 3.$$

Sol. The given system of equations can be written as  $Ax = b$ , where

$$A = \begin{pmatrix} 2 & 1 & -1 \\ 3 & 2 & 1 \end{pmatrix}, x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \text{ and } b = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

Since rank of  $A$  is 2, the maximum number of linearly independent columns of  $A$  is 2. Thus, we can take any of the following  $2 \times 2$  sub-matrices of  $A$ , as basic matrix  $B$  :

$$\begin{pmatrix} 2 & 1 \\ 3 & 2 \end{pmatrix}, \begin{pmatrix} 1 & -1 \\ 2 & 1 \end{pmatrix} \text{ and } \begin{pmatrix} 2 & -1 \\ 3 & 1 \end{pmatrix}$$

The variables not associated with the columns of these sub-matrices are, respectively,  $x_3$ ,  $x_1$  and  $x_2$ .

Considering  $B = \begin{pmatrix} 2 & 1 \\ 3 & 2 \end{pmatrix}$ , a basic solution to the given system is obtained by setting  $x_3 = 0$  and solving the system

$$\begin{pmatrix} 2 & 1 \\ 3 & 2 \end{pmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}.$$

Thus, basic solution to the given problem is

$$\text{(Basic)} x_1 = 1, x_2 = 0; \quad \text{(Non-basic)} x_3 = 0$$

Similarly, the other two solutions are :

$$\text{(Basic)} x_2 = 5/3, x_3 = -1/3; \quad \text{(Non-basic)} x_1 = 0.$$

$$\text{and} \quad \text{(Basic)} x_1 = 1, x_3 = 0 \quad \text{(Non-basic)} x_2 = 0$$

in each of the two basic solutions, at least one of the basic variables is zero. Hence, two of the basic solutions are degenerate solutions.

**Definition (Basic feasible solution).** A feasible solution to an L.P.P., which is also a basis solution to the problem is called a **basic feasible solution** to the L.P.P.

### Illustrations

1. In sample problem 1 observe that  $[5, 0, -1]$  is not a feasible solution. Only basic feasible solutions are :

$$(i) \quad x_2 = 5/3 \text{ and } x_3 = 2/3; \quad (ii) \quad x_1 = 2 \text{ and } x_2 = 1$$

2. In sample problem 2, the non-degenerate solution  $[0, 5/3, -1/3]$  is not feasible. Only basic feasible degenerate solutions are :

(i)  $x_1 = 1$  and  $x_2 = 0$

(ii)  $x_1 = 1$  and  $x_3 = 0$ .

**Definition (Associated cost vector).** Let  $x_B$  be a basic feasible solution to the L.P.P. :

$$\text{Maximize } z = cx \text{ subject to : } Ax = b \text{ and } x \geq 0$$

Then, the vector

$$c_B = (c_{B1}, c_{B2}, \dots, c_{Bm})$$

where  $c_{B1}$  are components of  $c$  associated with the basic variables, is called the **cost vector associated** with the basic feasible solution  $x_B$ .

It is obvious that the value of the objective function for the basic feasible solution  $x_B$ , is given by

$$z_0 = c_B x_B.$$

**Definition (Improved basic feasible solution).** Let  $x_B$  and  $\hat{x}_B$  be two feasible solutions to the standard L.P.P. Then  $\hat{x}_B$  is said to be an **improved basic feasible solution**, as compared to  $x_B$ , if

$$\hat{c}_B \hat{x}_B \geq c_B x_B$$

where  $\hat{c}_B$  is constituted of cost components corresponding to  $\hat{x}_B$ ,

**Definition (Optimum basic feasible solution).** A basic feasible solution  $x_B$  to the L.P.P. :

$$\text{Maximize } z = cx \text{ subject to : } Ax = b \text{ and } x \geq 0$$

is called an **optimum basic feasible solution** if  $z_0 = c_B x_B \geq z^*$  where  $z^*$  is the value of objective function for any feasible solution.

### PROBLEMS

3. Find all the basic feasible solutions of the equations

$$2x_1 + 6x_2 + 2x_3 + x_4 = 3$$

$$6x_1 + 4x_2 + 4x_3 + 6x_4 = 2$$